AG Series Electric Adaptive Gripper

AG-160-95 AG-105-145 DH-3

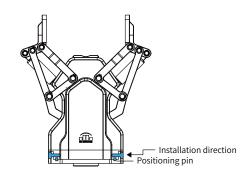


The AG series is a linkage-type adaptive electric gripper which is independently developed by DH-Robotics. With Plug& Play software many and exquisite structural design, AG series is a perfect solution to be applied with collabrative robots to grip work-pieces with different shapes in different industries.



Installation

1. Bottom installation: use bottom screw holes for installation



Product Features

● Envelope Adaptive Capture

The gripper linkage mechanism supports envelope adaptive grasping, which is more stable to grip round, spherical or special-shaped objects.

Plug & Play

It supports plug & play with most collaborative robot brands on the market which is easier to control and program.

Long Stroke

The biggest stroke of the AG series is up to 145 mm. One gripper can meet the grasping needs of objects of different sizes with good compatibility.

Application

Cooperate with collaborative robot or industrial robot to complete material handling, loading and unloading, assembly, testing, sorting and other tasks in auto parts, automation equipment, new energy and other industries.





Parameters

Product Parameter						
Gripping force (10~65 N					
Stroke	106 mm (parallel) 122 mm (centric)					
Recommended workpiece weight			* 1.8 kg			
Opening/Closin		0.7 s/0.7 s				
Repeat accuracy (position)			\pm 0.03 mm			
Noise emission		< 50 dB				
Weight			1.68 kg			
Driving method	Scre	Screw nut + gear drive + linkage mechanism				
Size	ize 213.5 mm x 170 mm x 118 mm				8 mm	
Working Environment						
Communication	e	Standard: TCP/IP, USB2.0, CAN2.0A Optional: EtherCAT				
Rated voltage		24 V DC \pm 10%				
Rated current		0.5 A				
Peak current		1 A				
IP class		IP 40				
Recommended environment 0~40°C, under 85% RH					% RH	
Certification				CE, FCC, RoHS		
Build-in Gripping Force Controller Adjustable	Position Adjustable	Speed Adjustable	Drop Detection	Plug & Play	Self-locking Mechanism	



Vertical Maximum Force			
Fz:	150 N		
Allowable Moment			
Mx:	2.5 N⋅m		
My:	2 N·m		
Mz:	3 N·m		

^{*}It depends on the shape of the grasping object, the material and friction of the contact surface, and the acceleration of the motion, if you have any questions, please contact us.

Finger rotate 90°

Technical Drawings

